

Risk-Based Comparison of Classification Systems

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Master's Thesis Presentation

Risk-Based
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Hypothetical Situation

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A broker classifies stocks as “Buy”, “Hold”, or “Sell”:

- Many small factors have begun to adversely affect stocks in a particular client’s portfolio
- Companies whose stocks may fail are unaware
- Broker applies classification algorithm to gathered data, classifying 85% of portfolio companies as “in severe danger of failing” (usually $< 10\%$)
- Broker doesn’t know if system is “best available”
- Instead of selling stocks immediately, she questions accuracy of data inputs and calls algorithm vendor to find out if something is wrong with “the system” she is using to classify stocks
- Brokerage loses time, portfolio value deteriorates

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- Background of ROC Analysis in Binary Classification
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- Partially Known Class Prevalences

3 Example Application

- Uniformly Distributed Class Prevalences
- Beta-Distributed Class Prevalences
- Discussion of Application Results

Confusion Matrices

Binary (Two-Class) Classification System

- Results of two-class (i.e., Class **1** *Positive*, Class **2** *Negative*) experiment or observational study applied to a set of validation data:

	Actual Class: 1	Actual Class: 2
Labeled Class: 1	TP	FP
Labeled Class: 2	FN	TN

- Calculate by-class decision frequencies using numbers of objects in Classes **1** and **2**:

	Actual Class: 1	Actual Class: 2
Labeled Class: 1	$\frac{TP}{M_1}$	$\frac{FN}{M_2}$
Labeled Class: 2	$\frac{FN}{M_1}$	$\frac{TN}{M_2}$

Transpose Stochastic Confusion Matrix

- Given the confusion matrix shown previously:

Confusion Matrix	Actual Class: 1	Actual Class: 2
Labeled Class: 1	$\frac{TP}{M_1}$	$\frac{FP}{M_2}$
Labeled Class: 2	$\frac{FN}{M_1}$	$\frac{TN}{M_2}$

- One entry per column represents all *information*:
- $TP + FN = N_1 \implies \frac{TP}{M_1} + \frac{FN}{M_1} = 1$
- $FP + TN = M_2 \implies \frac{FP}{M_2} + \frac{TN}{M_2} = 1$

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- Receiver Operating Characteristic (ROC) is the *information* estimated by a confusion matrix

Mathematical Framework

Multi-Class Classification System, Probability Space

- A set \mathbf{E} of possible experimental outcomes, or elementary events $e \in \mathbf{E}$, a sample space
- A finite set $\mathbf{L} = \{\ell_1, \ell_2, \ell_3, \dots, \ell_n\}$ of distinct labels
- Intermediate mappings between \mathbf{E} and \mathbf{L} :
 - A sensor $s: \mathbf{E} \rightarrow \mathbf{D}$ with data set \mathbf{D} as range
 - A processor $p: \mathbf{D}' \rightarrow \mathbf{F}$ mapping from \mathbf{D} to a set \mathbf{F} of features (usually real variables)
 - A classifier $c_\theta: \mathbf{F} \rightarrow \mathbf{L}$ with threshold parameter $\theta \in \Theta$, a *threshold set* of possible parameter settings
- The composition $A_\theta \equiv c_\theta \circ p \circ s: \mathbf{E} \rightarrow \mathbf{L}$ is the classification system with threshold parameter θ :

$$\mathbf{E} \xrightarrow{A_\theta} \mathbf{L} \equiv \mathbf{E} \xrightarrow{s} \mathbf{D} \xrightarrow{p} \mathbf{F} \xrightarrow{c_\theta} \mathbf{L}$$

- A probability space $(\mathbf{E}, \mathcal{E}, P)$ defined on σ -field \mathcal{E}

Events of Interest

Event Set Class Partition, Classification System Pre-Image

- Label set $\mathbf{L} = \{l_1, l_2, l_3, \dots, l_n\}$ induces a *partition*

$$\mathbf{E} = \bigcup_{j=1}^n \mathcal{E}_j \text{ of } \textit{disjoint} \text{ classes of event set } \mathbf{E}$$

- Property of class prevalences due to partition:

$$\sum_{j=1}^n P(\mathcal{E}_j) \equiv \sum_{j=1}^n p_j = 1$$

- Pre-image set function $A_\theta^{\natural} : \mathcal{L} \rightarrow \mathcal{E}$ given by:

$$A_\theta^{\natural}(\{l_i\}) \equiv \{e \in \mathbf{E} : A_\theta(e) = l_i\} \subset \mathbf{E}$$

where \mathcal{E} , \mathcal{L} are σ -fields over \mathbf{E} , \mathbf{L} , respectively
(using $^{\natural}$ instead of $^{-1}$ to avoid confusion)

Class-Conditional Probabilities

- $\mathbf{q}_{ij}(A_\theta) \equiv$ conditional probability that A_θ assigns label ℓ_i to an outcome e , *given that* e belongs to class \mathcal{E}_j , defined for $\mathbf{i}, \mathbf{j} = \mathbf{1}, \mathbf{2}, \mathbf{3}, \dots, \mathbf{n}$
- For \mathcal{E}_j with $P(\mathcal{E}_j) = \mathbf{0}$ (i.e., *a priori* probability zero):

$$\mathbf{q}_{ij}(A_\theta) \equiv \mathbf{0}, \quad \forall \mathbf{i} = \mathbf{1}, \mathbf{2}, \mathbf{3}, \dots, \mathbf{n}$$

- For \mathcal{E}_j with $\mathbf{p}_j > \mathbf{0}$ (i.e., *positive class prevalence*):

$$\mathbf{q}_{ij}(A_\theta) \equiv \frac{P\left(A_\theta^{\dagger}(\{\ell_i\}) \cap \mathcal{E}_j\right)}{P(\mathcal{E}_j)},$$
$$\forall \mathbf{i} = \mathbf{1}, \mathbf{2}, \mathbf{3}, \dots, \mathbf{n}$$

Important Matrix Notation

- Conditional Probability Matrix $\mathbf{Q}_{A,\theta} = \left[\mathbf{q}_{ij}(A_\theta) \right]_{ij}$ is the $\mathbf{n} \times \mathbf{n}$ matrix of class-conditional probabilities for a classification system A_θ

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- Cost Matrix $\mathbf{C}_A = \left[\mathbf{c}_{ij}(A) \right]_{ij}$ is the $\mathbf{n} \times \mathbf{n}$ matrix of costs or losses of occurrence of the events whose probabilities are $\mathbf{q}_{ij}(A_\theta)$, invariant for all $\theta \in \Theta$

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- Prevalence Matrix \mathbf{P} is an $\mathbf{n} \times \mathbf{n}$ *stochastic* matrix with each row the *same* ordered \mathbf{n} -tuple \mathbf{p}^T consisting of the class prevalences $\{\mathbf{p}_j\}_{j=1}^n$:

$$\mathbf{p} \equiv \begin{bmatrix} \mathbf{p}_1 \\ \vdots \\ \mathbf{p}_n \end{bmatrix} \implies \mathbf{P} = \begin{bmatrix} \mathbf{p}^T \\ \vdots \\ \mathbf{p}^T \end{bmatrix} = \begin{bmatrix} \mathbf{p}_1 & \cdots & \mathbf{p}_n \\ \vdots & & \vdots \\ \mathbf{p}_1 & \cdots & \mathbf{p}_n \end{bmatrix}_{\mathbf{n} \times \mathbf{n}}$$

Special Matrix Operators

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- Given two matrices \mathbf{U} and \mathbf{V} of size $\mathbf{s} \times \mathbf{r}$:

$$[\mathbf{U} \odot \mathbf{V}]_{ij} \equiv \mathbf{u}_{ij} \mathbf{v}_{ij}$$

is the (\mathbf{i}, \mathbf{j}) -element of the Hadamard Product, and the sum of all these is the Frobenius Dot Product:

$$\langle \mathbf{U}, \mathbf{V} \rangle_F \equiv \sum_{i=1}^{\mathbf{s}} \left[\sum_{j=1}^{\mathbf{r}} \mathbf{u}_{ij} \mathbf{v}_{ij} \right]$$

Special Matrix Operators

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- Given a matrix \mathbf{X} of size $\mathbf{s} \times \mathbf{r}$: $\int [\cdot] \mathbf{d}\mathbf{X} \equiv \int \dots \dots \int \dots \dots \int \int [\cdot] \mathbf{d}\mathbf{x}_{11} \mathbf{d}\mathbf{x}_{12} \dots \mathbf{d}\mathbf{x}_{1r} \dots \dots \mathbf{d}\mathbf{x}_{sr}$ is integration with respect to the vector $\mathbf{d}\mathbf{X}$ of all differential elements $\mathbf{d}\mathbf{x}_{ij}$ of variables in \mathbf{X}

Assumptions

Given a classification system A_θ :

Given a classification system A_θ and $\mathbf{i}, \mathbf{j} = 1, \dots, \mathbf{n}$:

- All *non-zero* class-conditional probabilities $q_{\mathbf{i}|\mathbf{j}}(A_\theta)$ are independent of all class prevalences \mathbf{p}_j

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- All *non-zero* class-conditional probabilities $q_{\mathbf{i}|\mathbf{j}}(A_\theta)$ are independent of all class prevalences \mathbf{p}_j
- All costs $c_{\mathbf{i}|\mathbf{j}}(A)$ are subjectively fixed and independent of all class prior probabilities $P(\mathcal{E}_j)$

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- All class-conditional probabilities $\mathbf{q}_{\mathbf{i}|\mathbf{j}}(A_\theta)$ are independent of the fixed costs $\mathbf{c}_{\mathbf{i}|\mathbf{j}}(A)$
- $\mathbf{Q}_{A,\theta}$, \mathbf{C}_A , and \mathbf{P} are *continuous random matrices* with marginal probability density functions $W_{\mathbf{Q}}(\mathbf{Q}_{A,\theta})$, $W_{\mathbf{C}}(\mathbf{C}_A)$, and $W_{\mathbf{P}}(\mathbf{P})$ satisfying $W_{\mathbf{Q},\mathbf{C},\mathbf{P}}(\mathbf{Q}_{A,\theta}, \mathbf{C}_A, \mathbf{P}) = W_{\mathbf{Q}}(\mathbf{Q}_{A,\theta}) W_{\mathbf{C}}(\mathbf{C}_A) W_{\mathbf{P}}(\mathbf{P})$

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- All costs $c_{ij}(A)$ are subjectively fixed and independent of all class prior probabilities $P(\xi_j)$
- All class-conditional probabilities $\mathbf{q}_{ij}(A_\theta)$ are independent of the fixed costs $\mathbf{c}_{ij}(A)$
- $\mathbf{Q}_{A,\theta}$, \mathbf{C}_A , and \mathbf{P} are *continuous random matrices* with marginal probability density functions $W_Q(\mathbf{Q}_{A,\theta})$, $W_C(\mathbf{C}_A)$, and $W_P(\mathbf{P})$ satisfying $W_{Q,C,P}(\mathbf{Q}_{A,\theta}, \mathbf{C}_A, \mathbf{P}) = W_Q(\mathbf{Q}_{A,\theta}) W_C(\mathbf{C}_A) W_P(\mathbf{P})$
- Any estimate $\widehat{\mathbf{Q}}_{A,\theta}$ of the conditional probability matrix $\mathbf{Q}_{A,\theta}$ is acceptable (i.e., substituting $\widehat{\mathbf{Q}}_{A,\theta} \approx \mathbf{Q}_{A,\theta}$ results in no appreciable error)

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- Given event set \mathbf{E} , label set \mathbf{L} , and threshold set Θ , a family of classification systems of form $A_\theta: \mathbf{E} \rightarrow \mathbf{L}$ is denoted by $\mathbb{A} = \{A_\theta: \theta \in \Theta\}$

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- Given conditional probability matrix $\mathbf{Q}_{A,\theta}$, cost matrix \mathbf{C}_A , and prevalence matrix \mathbf{P} , risk $R_{A,\theta}$ is:

$$\begin{aligned} R_{A,\theta} &= \left\langle \mathbf{Q}_{A,\theta}, (\mathbf{C}_A \odot \mathbf{P}) \right\rangle_F \\ &= \sum_{i=1}^n \sum_{j=1}^n \mathbf{q}_{ij}(A_\theta) \mathbf{c}_{ij}(A) \mathbf{p}_{ij} \\ &= \sum_{i=1}^n \sum_{j=1}^n \mathbf{q}_{ij}(A_\theta) \mathbf{c}_{ij}(A) \mathbf{p}_j \end{aligned}$$

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Two-Class ROC Analysis

- Recall confusion matrix as acceptable estimate of conditional probability matrix $\mathbf{Q}_{A,\theta}$:

$$\begin{bmatrix} tpr & fpr \\ fnr & tnr \end{bmatrix} \equiv \begin{bmatrix} \frac{TP}{M_1} & \frac{FP}{M_2} \\ \frac{FN}{M_1} & \frac{TN}{M_2} \end{bmatrix} \approx \begin{bmatrix} \mathbf{q}_{1|1}(A_\theta) & \mathbf{q}_{1|2}(A_\theta) \\ \mathbf{q}_{2|1}(A_\theta) & \mathbf{q}_{2|2}(A_\theta) \end{bmatrix}$$

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- If we vary θ over some range and plot points $\left(\mathbf{q}_{1|2}(A_\theta), \mathbf{q}_{1|1}(A_\theta)\right)$, we represent a ROC curve
- If threshold set Θ is continuous, a large sample of ROC vectors $\left(\mathbf{q}_{1|2}(A_\theta), \mathbf{q}_{1|1}(A_\theta)\right)$ approaches a smooth curve on the unit square

AUC: Area Under the ROC Curve

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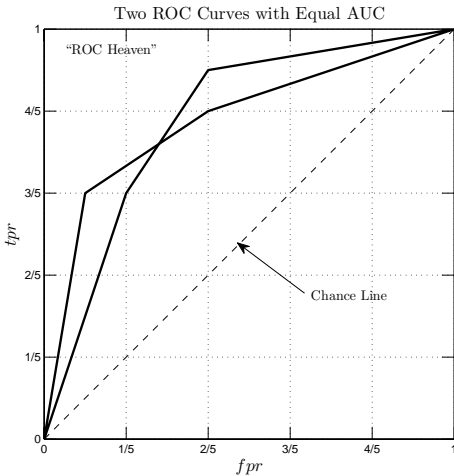


Figure: Two ROC Curves with Equal AUC

AUC for One ROC Point

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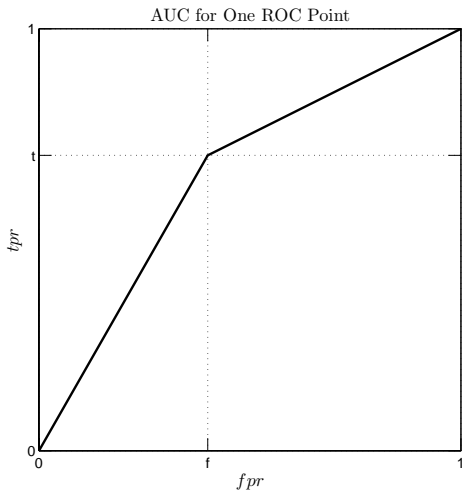


Figure: AUC for a Single ROC Point

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- $AUC = 1 - \frac{tpr + tnr}{2}$, or $1 -$ “skew-insensitive” accuracy under assumptions of equal class prevalences and so-called “zero-one” cost matrix (zeroes along diagonal)

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- Gini Coefficient—related to accuracy

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- Gini Coefficient—related to accuracy
- Matthews Correlation Coefficient—also related to accuracy
- Specificity, Sensitivity, Positive/Negative Predictive Values, False Discovery Rate, etc.

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- $AUC = 1 - \frac{tpr + tnr}{2}$, or $1 -$ “skew-insensitive” accuracy under assumptions of equal class prevalences and so-called “zero-one” cost matrix (zeroes along diagonal)
- Gini Coefficient—related to accuracy
- Matthews Correlation Coefficient—also related to accuracy
- Specificity, Sensitivity, Positive/Negative Predictive Values, False Discovery Rate, etc.
- In general, these are not robust to simultaneous changes in class prevalence and cost

Multi-Class ROC Analysis Methods

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- In extending to **3** dimensions, ROC vector has 6 points and cannot be visualized

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- Some have constructed a **3**-dimensional surface from the diagonals of the conditional probability matrix, ignoring off-diagonals to calculate Volume Under the ROC Surface (VUS)

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- Some have constructed a **3**-dimensional surface from the diagonals of the conditional probability matrix, ignoring off-diagonals to calculate Volume Under the ROC Surface (VUS)
- Some treat *either* cost or class prevalence as threshold parameters, but not *both*
- Note: no assumptions on independence are required for any of these measures, as they will be for ideas presented in this thesis

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Thorsen and Oxley, SPIE 2006

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- Thorsen and Oxley suggested ROC analysis minimizing Bayes Risk:

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- Thorsen and Oxley suggested ROC analysis minimizing Bayes Risk:



$$\min_{\mathbf{q} \in Q} \int_{\Gamma} \langle \mathbf{q}, \hat{\boldsymbol{\gamma}} \rangle \mathbf{W}(\boldsymbol{\gamma}) \, d\boldsymbol{\gamma}$$

where Q is a collection of ROC vectors and $\mathbf{W}(\boldsymbol{\gamma})$ is a *joint* weighting function on a cost-prior Hadamard Product vector $\hat{\boldsymbol{\gamma}} = \mathbf{c} \odot \hat{\mathbf{p}}$, either a probability density function or belief function

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- Requires knowledge of joint distribution of costs and prior probabilities

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- Requires knowledge of joint distribution of costs and prior probabilities
- *Expected value* of risk $\langle \mathbf{q}, \hat{\gamma} \rangle$ is Bayes Risk

Framework of ROC Risk Functional

Using matrices and dropping notation for A_θ ,

$E(R) \equiv E \left[\left\langle \mathbf{Q}, (\mathbf{C} \odot \mathbf{P}) \right\rangle_F \right]$ becomes:

$$\begin{aligned} & \int \int \int \left\langle \mathbf{Q}, (\mathbf{C} \odot \mathbf{P}) \right\rangle_F W_{\mathbf{Q}, \mathbf{C}, \mathbf{P}} d\mathbf{Q} d\mathbf{C} d\mathbf{P} \\ &= \int \int \int \sum_{i=1}^n \left(\sum_{j=1}^n \left[\mathbf{q}_{i|j} (\mathbf{c}_{i|j} \mathbf{p}_j) \right] \right) W_{\mathbf{Q}, \mathbf{C}, \mathbf{P}} d\mathbf{Q} d\mathbf{C} d\mathbf{P} \\ &= \sum_{i=1}^n \left[\sum_{j=1}^n \left(E[\mathbf{q}_{i|j}] \left[E[\mathbf{c}_{i|j}] E[\mathbf{p}_j] \right] \right) \right] \\ &= \left\langle \mathbf{E}[\mathbf{Q}_A], \left(\mathbf{E}[\mathbf{C}_A] \odot \mathbf{E}[\mathbf{P}_A] \right) \right\rangle_F \end{aligned}$$

where $\mathbf{E}[\cdot]$ is a *matrix* $[E(\cdot)]_{ij}$ of expected values

ROC Risk Functional

- Given an acceptable estimate $\widehat{\mathbf{Q}}_{A,\theta}$ of the conditional probability matrix $\mathbf{Q}_{A,\theta}$, we may substitute $\mathbf{E}[\widehat{\mathbf{Q}}_{A,\theta}] \approx \mathbf{Q}_{A,\theta}$, and we may also consider costs to be subjectively fixed

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- Define the ROC Risk functional as that threshold parameter θ such that the classification system $A_\theta \in \mathbb{A}$ minimizes Bayes risk over the family \mathbb{A} :

$$\arg \min_{\theta \in \Theta} \{E[R_{A,\theta}]\} = \arg \min_{\theta \in \Theta} \left\{ \left\langle \widehat{\mathbf{Q}}_{A,\theta}, \mathbf{C}_A \odot \mathbf{E}[\mathbf{P}] \right\rangle_F \right\}$$

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- Now we may estimate priors under fixed costs and acceptable conditional probability estimates

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- The marginal distribution of the last random variable may be found using the method of distributions or transformations, etc.
- Expected value for each class prevalence is $\frac{1}{3}$, general case $\frac{1}{n}$
- Assumption of equal priors implies this uniform distribution

Method of Choosing First Two Prevalences

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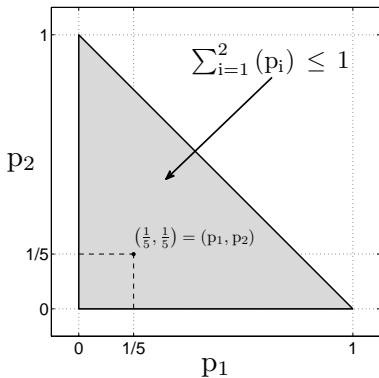


Figure: $\Delta_2 \equiv \left\{ \mathbf{p} \in [0, 1]^2 : \sum_{i=1}^2 p_i \leq 1 \right\}$

Method of Choosing Third Class Prevalence

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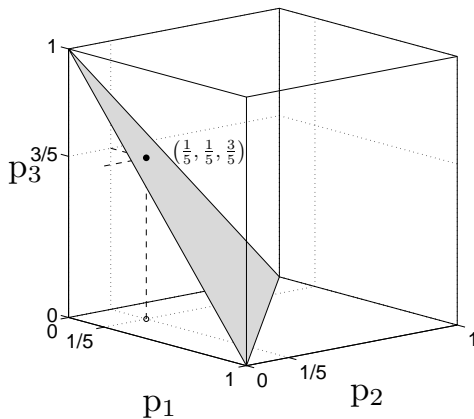


Figure: $\Delta_3 \equiv \left\{ \mathbf{p} \in [0, 1]^3 : \sum_{i=1}^3 p_i \leq 1 \right\}$

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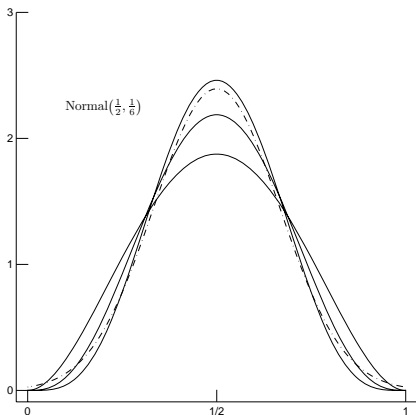


Figure: Beta Approximation to Normal($\frac{1}{2}, \frac{1}{6}$)

Beta Distribution as Normal Approximation

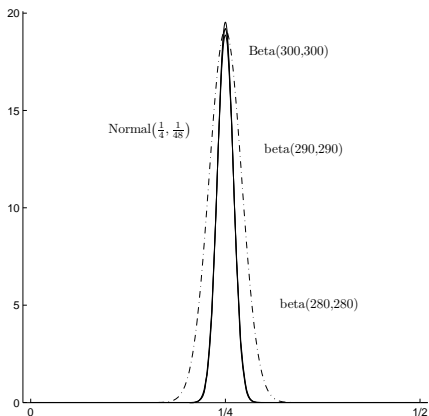


Figure: Beta Approximation to Normal($\frac{1}{4}, \frac{1}{48}$)

Bivariate Beta Joint Prevalence Distribution

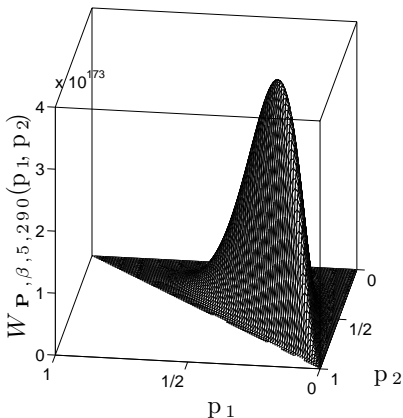


Figure:

$$W_{P, \beta, 5, 290}(p_1, p_2) \approx \frac{1.197 \times 10^{178} (p_1 - p_1^2)^4 (p_2 - p_1 p_2 - p_2^2)^{289}}{(1 - p_1)^{579}}$$

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- General Beta distributions are very flexible fixed-support distributions

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- General Beta distributions are very flexible fixed-support distributions
- Class distribution of third prevalence too difficult to derive

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- In general, tried to maximize overall size of training data

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- General Beta distributions are very flexible fixed-support distributions
- Class distribution of third prevalence too difficult to derive
- Order of choosing classes not randomly assigned because distribution has shape
- In general, tried to maximize overall size of training data
- Could use a non-standard weighting, such as belief functions

Notes on Testing of Assumptions

- Using Probabilistic Neural Network and Lachenbruch Holdout Method to estimate class-conditional probabilities as average over repeated random draws from prevalence distribution

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- Power curve analysis through Monte Carlo simulation:
 - Alternative two-tailed hypothesis: Kendall's Tau $\geq \mathbf{0.4}$ in absolute value
 - P-values of $\leq \mathbf{0.15}$ assumed significant
 - **99%** confidence interval for **37**-sample power: **(0.8083, 0.8282)**

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- Probabilistic Neural Net (PNN) uses spread parameter for thresholds

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- Probabilistic Neural Net (PNN) uses spread parameter for thresholds
- PNN yields stable results in replication (unlike Feed-Forward)

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- Used Fisher Iris Data, equal class populations of **50** each
- Stored resulting class prevalences and conditional probabilities for correlation testing
- Used standardized form (pre-processed) data, so spread varied from ≈ 0 to **1** in **10** steps

Notes on Cost Regimes Used

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Partially Known Priors

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Cost Set 1	Actual Class: 1	Actual Class: 2	Actual Class: 3
Labeled Class: 1	0	1	1
Labeled Class: 2	2	0	1
Labeled Class: 3	2	1	0

Cost Set 2	Actual Class: 1	Actual Class: 2	Actual Class: 3
Labeled Class: 1	1	10	2
Labeled Class: 2	2	1	2
Labeled Class: 3	2	10	1

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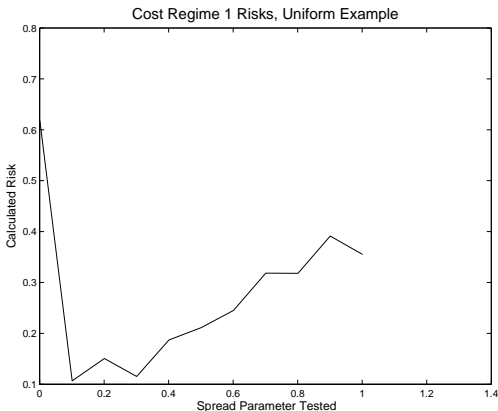


Figure: Risk for Cost Regime 1, Uniform Application

Results of Risk Minimization, Uniform Cost 2

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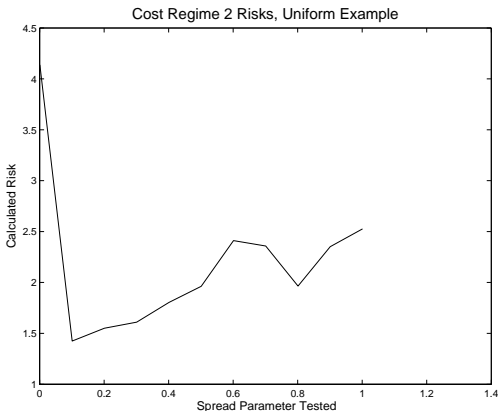


Figure: Risk for Cost Regime 2, Uniform Application

Results of Uniform Distribution Experiment

Spread parameter $\theta = \mathbf{0.101}$ minimized cost over two separate fixed cost scenarios

Mean Absolute Value of Kendall's Tau Coefficients:

Kendall's Tau	Actual Class: 1	Actual Class: 2	Actual Class: 3
Labeled Class: 1	0.34	0.14	0.06
Labeled Class: 2	0.34	0.66	0.58
Labeled Class: 3	0.00	0.59	0.63

Mean p-Value matrix for Kendall's Tau Coefficients:

p-values	Actual Class: 1	Actual Class: 2	Actual Class: 3
Labeled Class: 1	0.16	0.59	0.91
Labeled Class: 2	0.16	0.00	0.09
Labeled Class: 3	1.00	0.09	0.00

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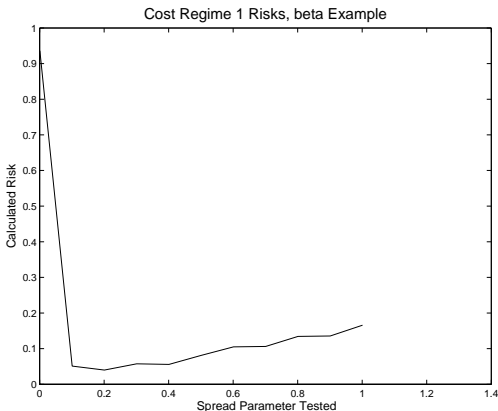


Figure: Risk for Cost Regime 1 , beta Application

Results of Risk Minimization, beta Cost 2

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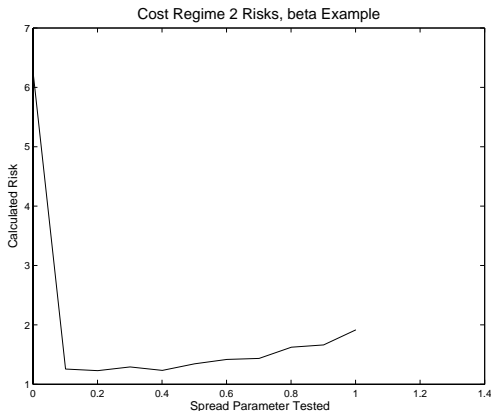


Figure: Risk for Cost Regime 2, beta Application

Results of beta Distribution Experiment

Spread parameter $\theta = \mathbf{0.201}$ minimized cost over two separate fixed cost scenarios

Mean Absolute Value of Kendall's Tau Coefficients:

Kendall's Tau	Actual Class: 1	Actual Class: 2	Actual Class: 3
Labeled Class: 1	0.13	0.18	0.05
Labeled Class: 2	0.13	0.26	0.15
Labeled Class: 3	0.00	0.20	0.20

Mean p-Value matrix for Kendall's Tau Coefficients:

p-values	Actual Class: 1	Actual Class: 2	Actual Class: 3
Labeled Class: 1	0.58	0.48	0.91
Labeled Class: 2	0.58	0.20	0.39
Labeled Class: 3	1.00	0.31	0.30

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- Assumptions allow risk calculation without knowing joint distribution of all variables

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- Assumptions met better in beta application
- Assumptions allow risk calculation without knowing joint distribution of all variables
- How important is independence?

Summary

- The **mathematical framework** of ROC Analysis is necessary to enable precise quantification of risk when competing classification systems

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- The **mathematical framework** of ROC Analysis is necessary to enable precise quantification of risk when competing classification systems
- The **ROC Risk Functional (RRF)** is a precise, general, and flexible measure of performance

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- The **mathematical framework** of ROC Analysis is necessary to enable precise quantification of risk when competing classification systems
- The **ROC Risk Functional (RRF)** is a precise, general, and flexible measure of performance
- The **application** of the RRF is simple and straightforward

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 - Belief functions may be more accessible to normal users

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 - Other probability distributions beyond the Beta distribution may be better suited to certain situations

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 - Other probability distributions beyond the Beta distribution may be better suited to certain situations
 - Distributions of costs and ROC information may be analyzed separately
 - Method of training classifiers may merit wider application